

# Theoretical Aspects of Intruder Search

Course Wintersemester 2015/16

Introduction

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# Organisation

- Lecture: Tuesday 16:15 to 17:45
- Exercise groups: Starting next week 28/29th
  - Wednesday: 14-16
  - Thursday: 10-12
- Sign in
- Manuscript on the webpage
- Slides on the webpage
- Exercises
- Today: Introduction, different topics

# Main problems and intention

- Evader/Intruder versus Searcher/Guard
- Escaping/Intruding versus Catching/Avoidance
- Game, Competition
- Different Scenarios: Environment, Facilities, Goal, Model
- Discrete, Continuous, Geometry, Combinatorics
- Interpretation: Possible Position of the Intruder, Decontamination, Firefighting

# Theoretical Aspects

- Algorithmic track
- Computational complexity
- Correctness or Failure
- Efficiency
- Optimality
- Prerequisites: Algorithms, Datastructure, Analysis, Complexity, Computability
- Models, Methods, Proof Techniques, Tools
- Today Introduction

# Example I: Polygon, Safe an Area, Complexity

- Continuous Problem
- Complexity Result
- NP-hardness
- Reduction

*Optimal-Closing-Sequence:*

**Instance:** Simple polygon, set of  $n$  intruders, set of  $m$  doors to be closed successively time  $c_i$ , safes area  $A_i$ .

**Output:** Compute the optimal sequence of doors that has to be closed for maximizing the are the area safed.

# Reduction: Subset-Sum with treshhold

*Subset-Sum:*

**Instance:**  $n$  integer numbers  $a_1, a_2, \dots, a_n$ , integer treshhold  $t$

**Output:** Sum of a subset of  $a_1, a_2, \dots, a_n$  as close as possible to  $t$ , not exceeding  $t$ .

- Reduction to *Optimal-Closing-Sequence*
- Construct Instance in polynomial time
- Solution for *Optimal-Closing-Sequence*  $\Leftrightarrow$  Solution for *Subset-Sum*

# Reduction: Subset-Sum with threshold

- Circle radius  $r$ , center  $s$ , intruder start at  $s$
- Chords of length  $a_i$ , polygonal chain:  $A_i, B_i, C'_i, D_i$
- Door  $d_i$  safes Area  $A_i = \frac{ha_i}{4}$
- Speed  $v(t + 0.5) = r$  for every Intruder
- Choose  $r$  so that  $vt < x_i = \sqrt{r^2 - \left(\frac{a_i}{2}\right)^2}$
- Substituting  $v$  by  $\frac{r}{(t+0.5)}$ :

$$\left(\frac{a_i}{2}\right)^2 < \left(1 - \frac{t^2}{(t + 0.5)^2}\right) r^2$$





# Reduction: Subset-Sum with treshold

**Theorem 1:** Computing an optimal-enclosurement-sequence is NP-hard.

Proof: Reduction from Subset-Sum, Equivalence!

# Example II: Grid Graph

- Discrete Problem
- Correctness/Failure
- Structural Properties

## *Evader-Enclosurement in Grid-Graphs*

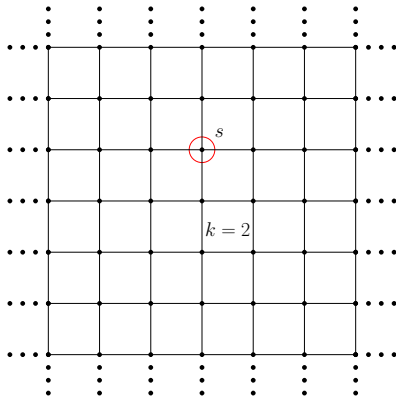
**Instance:** A rectangular grid, a start vertex  $s$  of the evader and  $k$  protecting guards per time step.

**Output:** Compute an efficient protection strategy that encloses the evader (and finally find the evader).

A Two Player Game!

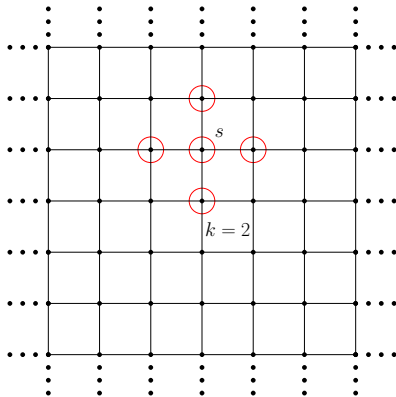
# Example II: Grid Graph, $k = 2$

Evader moves (4Neighborhood), Guards will be placed



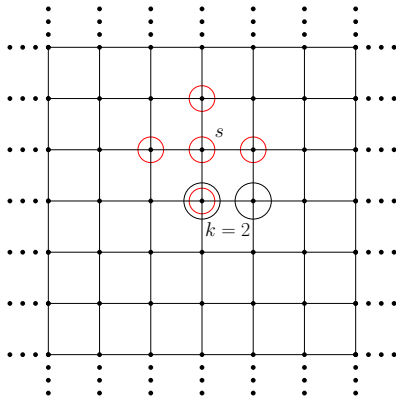
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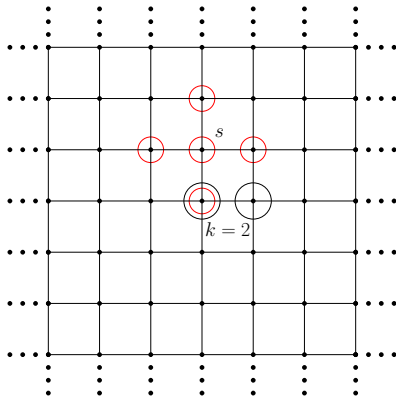
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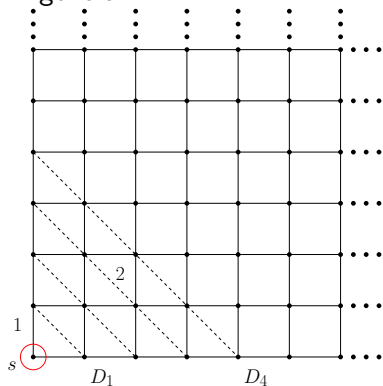
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Example Applet! Enclosing the Evader first!

# Example II: Grid Graph, $k = 1$

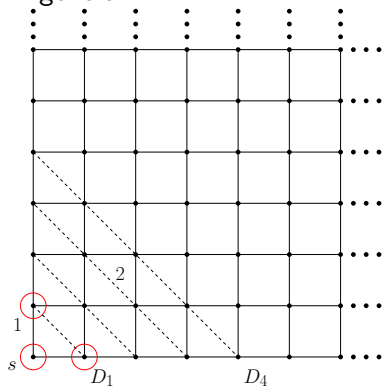
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Step I:  $r_l$  blocked cells in  $D_{l+1}, D_{l+2}, \dots$   
 $B_l \subseteq D_l$  burning cells in  $D_l$

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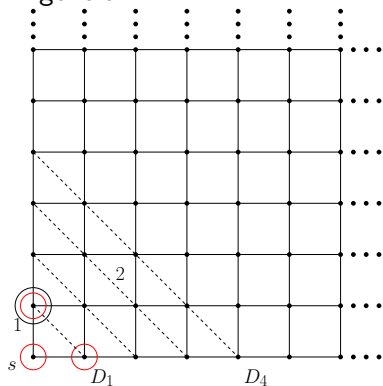


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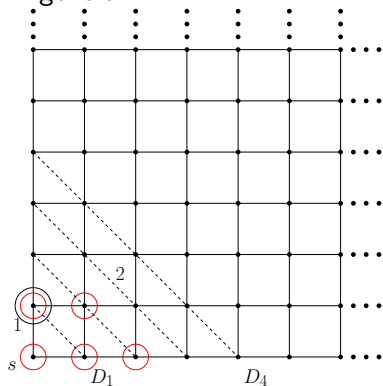
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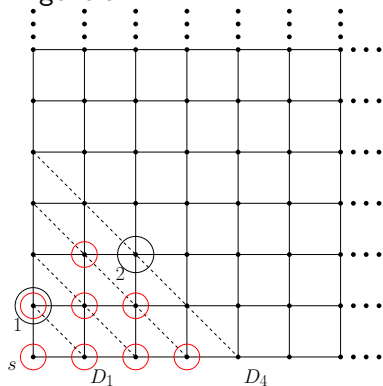


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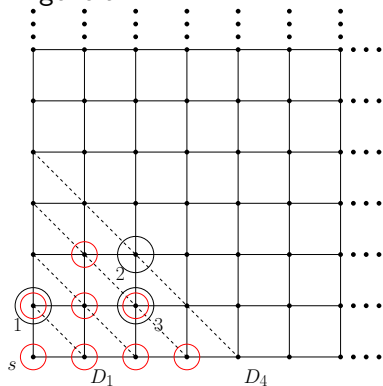
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- Move of the evader:  $B'_{l+1} = 1 + r_l - x + 1$

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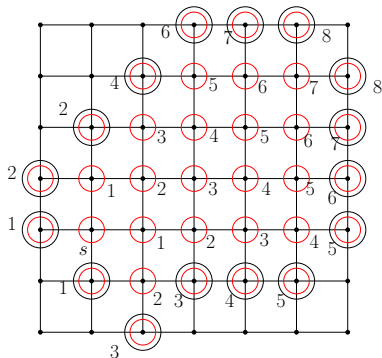
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- Block of the guard in  $D_{l_1}$ :  $l_1 > l + 1$   
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**Lemma 3:** For  $k = 2$  there is a successful enclosure strategy, that encloses the evader after 8 steps. After 9 additional steps, the evader will be found.

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Firefigthing interpretation! Outside the fire!

**Lemma 3:** For the outbreak of a fire on a single source in a grid and the usage of two firefighters per time step any successful strategy encloses an area of at least 18 burning vertices. This bound is tight.

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# Example II: Grid Graph, $k = 2$

Firefigthing interpretation! Integer LP for  $l \leq 8$ ,  $T \leq 9$

$$\text{Min } \sum_{v \in L} b_{v,T}$$

$$b_{v,t} + d_{v,t} - b_{w,t-1} \geq 0 \quad : \quad \forall v \in L, v \in N(w), 1 \leq t \leq T$$

$$b_{v,t} + d_{v,t} \leq 1 \quad : \quad \forall v \in L, 1 \leq t \leq T$$

$$b_{v,t} - b_{v,t-1} \geq 0 \quad : \quad \forall v \in L, 1 \leq t \leq T$$

$$d_{v,t} - d_{v,t-1} \geq 0 \quad : \quad \forall v \in L, 1 \leq t \leq T$$

$$\sum_{v \in L} (d_{v,t} - d_{v,t-1}) \geq 2 \quad : \quad \forall 1 \leq t \leq T$$

$$b_{v,0} = 1 \quad : \quad v \in L \text{ is the origin } (0,0)$$

$$b_{v,0} = 0 \quad : \quad v \in L \text{ is not the origin } (0,0)$$

$$d_{v,0} = 0 \quad : \quad \forall v \in L$$

$$d_{v,t}, b_{v,t} \in \{0,1\} \quad : \quad \forall v \in L, 1 \leq t \leq T$$

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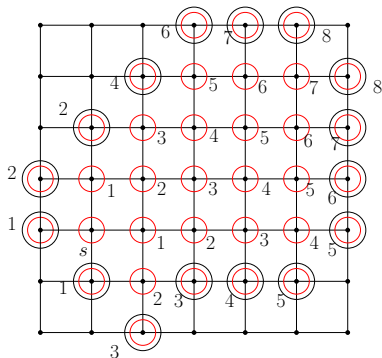
**Lemma 4:** For the outbreak of a fire on a single source in a grid and the usage of two firefighters per time step any successful strategy encloses an area of at least 18 burning vertices. This bound is tight.

Optimal solution by LP solver:

## Example II: Grid Graph, $k = 2$

**Lemma 4:** For the outbreak of a fire on a single source in a grid and the usage of two firefighters per time step any successful strategy encloses an area of at least 18 burning vertices. This bound is tight.

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# Example III: Continuous Firefigthing

## *Geometric Firefigther Problem*

**Instance:** A circle with center  $C$  of radius  $A$  that grows with unit speed. An agent who builds a firebreak with speed  $v > 1$

**Output:** Compute a strategy that finally fully enclose the spreading fire.

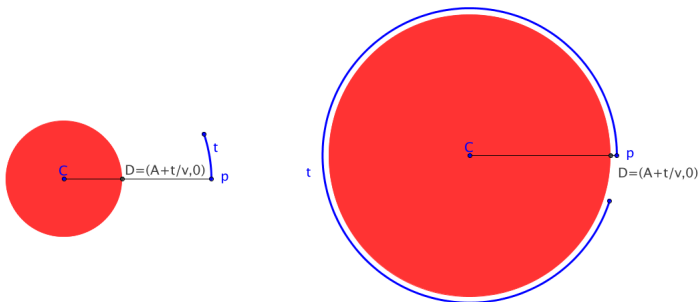
# Example III: Continuous Firefighting

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A circular strategy!



# Example III: Continuous Firefigthing

**Lemma 5:** Enclosing a fire of extension  $A$  with a single circular loop around the source of the fire is possible, if and only if the speed  $v$  of the firefigther is larger than  $2\pi$ .

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GeoGebra Simulation

# Example IV: Firefigthing Grid-World Simulation

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**Instance:** Grid contamination of size  $B$ , spreads 4Neighborhood after  $n$  time steps. Agent cleans a cell, builds a wall cell and leaves the cell within  $b$  time steps.

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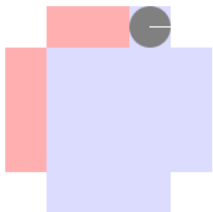
Example:  $n = 30$ ,  $b = 5$ ,  $B = 3 \times 3$

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# Example IV: Firefighthing Grid-World Simulation

**Conjecture 1:** For a grid fire that spreads after  $n$  time steps and an agent that builds a wall within  $b$  time steps, the spiral strategy only succeeds if  $b < \frac{n-1}{2}$  holds.

By simulation!